

Vector Spaces, Span, and Basis

1. Are the vectors

$$\mathbf{v}_1 = \begin{pmatrix} -1 \\ 0 \\ 2 \end{pmatrix}, \mathbf{v}_2 = \begin{pmatrix} 2 \\ 1 \\ 0 \end{pmatrix}, \mathbf{v}_3 = \begin{pmatrix} 1 \\ -2 \\ -1 \end{pmatrix}$$

linearly independent?

2. Do the vectors \mathbf{v}_1 , \mathbf{v}_2 , and \mathbf{v}_3 form a basis in \mathbb{R}^3 ?

3. Decompose the vector

$$\mathbf{u} = \begin{pmatrix} 7 \\ -5 \\ -7 \end{pmatrix}$$

onto the vectors \mathbf{v}_1 , \mathbf{v}_2 , and \mathbf{v}_3 .

4. Are the coefficients you found in Problem 3 the only ones that decompose \mathbf{u} over the vectors \mathbf{v}_1 , \mathbf{v}_2 , and \mathbf{v}_3 ?

5. Verify that the vectors

$$\mathbf{v}_1 = \begin{pmatrix} -1 \\ 1 \\ 1 \end{pmatrix}, \mathbf{v}_2 = \begin{pmatrix} 1 \\ -1 \\ 2 \end{pmatrix}, \mathbf{v}_3 = \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}$$

are mutually orthogonal.

6. Are the above vectors orthonormal?

7. Make the vectors \mathbf{v}_1 , \mathbf{v}_2 , and \mathbf{v}_3 into an orthonormal set.

8. Are the vectors $\hat{\mathbf{v}}_1$, $\hat{\mathbf{v}}_2$, and $\hat{\mathbf{v}}_3$ a basis for \mathbb{R}^3 ? How about the vectors \mathbf{v}_1 , \mathbf{v}_2 , and \mathbf{v}_3 ?

9. Decompose the vector

$$\mathbf{u} = \begin{pmatrix} 3 \\ 4 \\ -2 \end{pmatrix}$$

onto the basis vectors \hat{v}_1 , \hat{v}_2 , and \hat{v}_3 .

10. Given vectors

$$x_1 = \begin{pmatrix} -2 \\ 1 \end{pmatrix}, \quad x_2 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

calculate the vector that is the projection of x_2 onto x_1 .

11. Using your answer to Question 6, find a vector nearest to x_2 that is orthogonal to x_1 .

12. **CHALLENGE:** Look back at our proof of the theorem for decomposing a vector over an orthonormal basis using dot products. Can we use dot products to decompose over a basis where all vectors are orthogonal but not normalized?

Solutions

1. Are the vectors

$$\mathbf{v}_1 = \begin{pmatrix} -1 \\ 0 \\ 2 \end{pmatrix}, \mathbf{v}_2 = \begin{pmatrix} 2 \\ 1 \\ 0 \end{pmatrix}, \mathbf{v}_3 = \begin{pmatrix} 1 \\ -2 \\ -1 \end{pmatrix}$$

linearly independent?

Let's form a matrix \mathbf{V} using the vectors as columns.

$$\mathbf{V} = \begin{pmatrix} -1 & 2 & 1 \\ 0 & 1 & -2 \\ 2 & 0 & -1 \end{pmatrix}$$

This matrix has three rows and three columns. If all three columns are linearly independent, the matrix will have rank three.

$$\begin{aligned} \begin{pmatrix} -1 & 2 & 1 \\ 0 & 1 & -2 \\ 2 & 0 & -1 \end{pmatrix} &\xrightarrow{-R_1} \begin{pmatrix} 1 & -2 & -1 \\ 0 & 1 & -2 \\ 2 & 0 & -1 \end{pmatrix} \\ &\xrightarrow{-2R_1 \rightarrow R_3} \begin{pmatrix} 1 & -2 & -1 \\ 0 & 1 & -2 \\ 0 & 4 & 1 \end{pmatrix} \\ &\xrightarrow{-4R_2 \rightarrow R_3} \begin{pmatrix} 1 & -2 & -1 \\ 0 & 1 & -2 \\ 0 & 0 & 9 \end{pmatrix} \\ &\xrightarrow{(1/9)R_3} \begin{pmatrix} 1 & -2 & -1 \\ 0 & 1 & -2 \\ 0 & 0 & 1 \end{pmatrix} \end{aligned}$$

The reduced form of \mathbf{V} shows that $\text{rank}(\mathbf{V}) = 3$, so the vectors are linearly independent.

2. Do the vectors \mathbf{v}_1 , \mathbf{v}_2 , and \mathbf{v}_3 form a basis in \mathbb{R}^3 ?

Yes. The space \mathbb{R}^3 has dimension three, and we have three vectors. We know from the previous question that these three vectors are linearly independent. Combined, these facts prove that the vectors are a basis for \mathbb{R}^3 . Since they are a basis, we also know that the vectors span \mathbb{R}^3 .

3. Decompose the vector

$$\mathbf{u} = \begin{pmatrix} 7 \\ -5 \\ -7 \end{pmatrix}$$

onto the vectors \mathbf{v}_1 , \mathbf{v}_2 , and \mathbf{v}_3 .

We are looking for scalars a_1 , a_2 , and a_3 such that

$$a_1\mathbf{v}_1 + a_2\mathbf{v}_2 + a_3\mathbf{v}_3 = \mathbf{u}$$

which is equivalent to solving the linear system

$$\mathbf{V}\mathbf{a} = \mathbf{u}$$

where \mathbf{V} is a matrix with columns \mathbf{v}_1 , \mathbf{v}_2 , and \mathbf{v}_3 ; and \mathbf{a} is a vector of the scalars a_1 , a_2 , and a_3 :

$$\begin{pmatrix} -1 & 2 & 1 \\ 0 & 1 & -2 \\ 2 & 0 & -1 \end{pmatrix} \begin{pmatrix} a_1 \\ a_2 \\ a_3 \end{pmatrix} = \begin{pmatrix} 7 \\ -5 \\ -7 \end{pmatrix}$$

We can solve this by Gaussian elimination to find that $a_1 = -2$, $a_2 = 1$, and $a_3 = 3$.

4. Are the coefficients you found in Problem 3 the only ones that decompose \mathbf{u} over the vectors \mathbf{v}_1 , \mathbf{v}_2 , and \mathbf{v}_3 ?

Yes. Since the vectors \mathbf{v}_1 , \mathbf{v}_2 , and \mathbf{v}_3 are a basis, the decomposition of any vector onto them is unique.

5. Verify that the vectors

$$\mathbf{v}_1 = \begin{pmatrix} -1 \\ 1 \\ 1 \end{pmatrix}, \mathbf{v}_2 = \begin{pmatrix} 1 \\ -1 \\ 2 \end{pmatrix}, \mathbf{v}_3 = \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}$$

are mutually orthogonal.

The vectors are mutually orthogonal if every vector is orthogonal to every other vector. We can check orthogonality by computing dot products.

$$\mathbf{v}_1 \cdot \mathbf{v}_2 = (-1)(1) + (1)(-1) + (1)(2) = 0$$

$$\mathbf{v}_1 \cdot \mathbf{v}_3 = (-1)(1) + (1)(1) + (1)(0) = 0$$

$$\mathbf{v}_2 \cdot \mathbf{v}_3 = (1)(1) + (-1)(1) + (2)(0) = 0$$

6. Are the above vectors orthonormal?

We know the vectors are mutually orthogonal. For the vectors to be an orthonormal set, every vector needs to be a unit vector.

$$\|\mathbf{v}_1\| = \sqrt{(-1)^2 + 1^2 + 1^2} = \sqrt{3} \neq 1$$

$$\|\mathbf{v}_2\| = \sqrt{1^2 + (-1)^2 + (2)^2} = \sqrt{6} \neq 1$$

$$\|\mathbf{v}_3\| = \sqrt{1^2 + 1^2 + 0^2} = \sqrt{2} \neq 1$$

None of the vectors are unit vectors. We knew the vectors were not an orthonormal set after computing the first magnitude.

7. Make the vectors \mathbf{v}_1 , \mathbf{v}_2 , and \mathbf{v}_3 into an orthonormal set.

We showed that the three vectors are mutually orthogonal. All that remains is to normalize each vector by dividing by its magnitude.

$$\hat{\mathbf{v}}_1 = (1/\sqrt{3})\mathbf{v}_1$$

$$\hat{\mathbf{v}}_2 = (1/\sqrt{6})\mathbf{v}_2$$

$$\hat{\mathbf{v}}_3 = (1/\sqrt{2})\mathbf{v}_3$$

8. Are the vectors $\hat{\mathbf{v}}_1$, $\hat{\mathbf{v}}_2$, and $\hat{\mathbf{v}}_3$ a basis for \mathbb{R}^3 ? How about the vectors \mathbf{v}_1 , \mathbf{v}_2 , and \mathbf{v}_3 ?

A basis in \mathbb{R}^3 requires three vectors. The vectors $\hat{\mathbf{v}}_1$, $\hat{\mathbf{v}}_2$, and $\hat{\mathbf{v}}_3$ are mutually orthogonal, so they are also linearly independent (see the beginning of § 11.5). Any three linearly independent vectors form a basis in \mathbb{R}^3 . This argument requires only that the vectors be mutually orthogonal, not orthonormal, so the vectors \mathbf{v}_1 , \mathbf{v}_2 , and \mathbf{v}_3 also form a basis in \mathbb{R}^3 .

9. Decompose the vector

$$\mathbf{u} = \begin{pmatrix} 3 \\ 4 \\ -2 \end{pmatrix}$$

onto the basis vectors $\hat{\mathbf{v}}_1$, $\hat{\mathbf{v}}_2$, and $\hat{\mathbf{v}}_3$.

We are looking for coefficients a_1 , a_2 , and a_3 such that

$$\mathbf{u} = a_1\hat{\mathbf{v}}_1 + a_2\hat{\mathbf{v}}_2 + a_3\hat{\mathbf{v}}_3$$

Our basis is orthonormal so we can apply the shortcut formula using dot

products.

$$\begin{aligned}a_1 &= \mathbf{u} \cdot \hat{\mathbf{v}}_1 \\&= \begin{pmatrix} 3 \\ 4 \\ -2 \end{pmatrix} \cdot \frac{1}{\sqrt{3}} \begin{pmatrix} -1 \\ 1 \\ 1 \end{pmatrix} \\&= (-3 + 4 - 2)/\sqrt{3} = -1/\sqrt{3} \\a_2 &= \mathbf{u} \cdot \hat{\mathbf{v}}_2 \\&= \begin{pmatrix} 3 \\ 4 \\ -2 \end{pmatrix} \cdot \frac{1}{\sqrt{6}} \begin{pmatrix} 1 \\ -1 \\ 2 \end{pmatrix} \\&= (3 - 4 - 4)/\sqrt{6} = -5/\sqrt{6} \\a_3 &= \mathbf{u} \cdot \hat{\mathbf{v}}_3 \\&= \begin{pmatrix} 3 \\ 4 \\ -2 \end{pmatrix} \cdot \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} \\&= (3 + 4 + 0)/\sqrt{2} = 7/\sqrt{2}\end{aligned}$$

We can confirm that

$$\begin{aligned}&a_1 \hat{\mathbf{v}}_1 + a_2 \hat{\mathbf{v}}_2 + a_3 \hat{\mathbf{v}}_3 \\&= -\frac{1}{\sqrt{3}} \times \frac{1}{\sqrt{3}} \begin{pmatrix} -1 \\ 1 \\ 1 \end{pmatrix} - \frac{5}{\sqrt{6}} \times \frac{1}{\sqrt{6}} \begin{pmatrix} 1 \\ -1 \\ 2 \end{pmatrix} + \frac{7}{\sqrt{2}} \times \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} \\&= -\frac{1}{3} \begin{pmatrix} -1 \\ 1 \\ 1 \end{pmatrix} - \frac{5}{6} \begin{pmatrix} 1 \\ -1 \\ 2 \end{pmatrix} + \frac{7}{2} \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} \\&= \begin{pmatrix} 3 \\ 4 \\ -2 \end{pmatrix} = \mathbf{u}\end{aligned}$$

10. Given vectors

$$\mathbf{x}_1 = \begin{pmatrix} -2 \\ 1 \end{pmatrix}, \quad \mathbf{x}_2 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

calculate the vector that is the projection of \mathbf{x}_2 onto \mathbf{x}_1 .

$$\begin{aligned} \text{proj}_{\mathbf{x}_1}(\mathbf{x}_2) &= \frac{\mathbf{x}_2 \cdot \mathbf{x}_1}{\mathbf{x}_1 \cdot \mathbf{x}_1} \mathbf{x}_1 \\ &= \frac{1 \times -2 + 1 \times 1}{-2 \times -2 + 1 \times 1} \mathbf{x}_1 \\ &= \begin{pmatrix} 2/5 \\ -1/5 \end{pmatrix} \end{aligned}$$

11. Using your answer to Question 6, find a vector nearest to \mathbf{x}_2 that is orthogonal to \mathbf{x}_1 .

The vector $\mathbf{x}_2 - \text{proj}_{\mathbf{x}_1}(\mathbf{x}_2)$ is orthogonal to the vector \mathbf{x}_1 .

$$\begin{aligned} \mathbf{x}_2 - \text{proj}_{\mathbf{x}_1}(\mathbf{x}_2) &= \begin{pmatrix} 1 \\ 1 \end{pmatrix} - \begin{pmatrix} 2/5 \\ -1/5 \end{pmatrix} \\ &= \begin{pmatrix} 3/5 \\ 6/5 \end{pmatrix} \end{aligned}$$

To verify, we compute the dot product between our new vector and \mathbf{x}_1 .

$$\begin{pmatrix} 3/5 \\ 6/5 \end{pmatrix} \cdot \begin{pmatrix} -2 \\ 1 \end{pmatrix} = -6/5 + 6/5 = 0$$

12. CHALLENGE: Look back at our proof of the theorem for decomposing a vector over an orthonormal basis using dot products. Can we use dot

products to decompose over a basis where all vectors are orthogonal but not normalized?

We use the normality of the vectors after we show that

$$\mathbf{u} \cdot \hat{\mathbf{v}}_i = a_i \hat{\mathbf{v}}_i \cdot \hat{\mathbf{v}}_i = a_i \|\hat{\mathbf{v}}_i\|^2$$

If the basis vectors were orthogonal but not normalized, we would instead have

$$\mathbf{u} \cdot \mathbf{v}_i = a_i \mathbf{v}_i \cdot \mathbf{v}_i = a_i \|\mathbf{v}_i\|^2$$

Here we are unable to assume that $\|\mathbf{v}_i\|^2 = 1$ since \mathbf{v}_i is not a normal vector. But we can still solve for the coefficient a_i .

$$a_i = (\mathbf{u} \cdot \mathbf{v}_i) / \|\mathbf{v}_i\|^2$$

The above formula uses only a dot product and a norm to compute each coefficient. These are far easier calculations than solving the linear system $\mathbf{V}\mathbf{a} = \mathbf{u}$ for non-orthogonal basis vectors. The power of orthonormal basis vectors comes from their orthogonality, not their normality.